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VAL3 is a high-level programming

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update Val3 system Purpose: Be able to
set a communication with CPU board in
order to update the VAL3 language.

Necessary tools: - RJ45 cross over cable -

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VAL3 language version release to install

Procedure to update Val3 system

This license grants access to all the functionalities required to perform realistic simulations involving one or more robots: High end VAL 3 program editor with advanced functionalities inspired from the latest computer

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languages editor (such as online debugging, auto-completion of code line, code snippets, on-the-fly syntax check)

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an instruction in the list of VAL3 instructions. It is possible to insert a breaking point in an instruction (see paragraph 6.10.3). It is possible to insert a breaking point in an instruction (see paragraph 6.10.3).

**STAUBLI CS8C INSTRUCTION
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Stäubli's 6 axis robots deliver increased dexterity and flexibility. The compact arm and large work envelope allow maximum utilization of cell workspace.

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Documented ROS-Industrial VAL3 driver for interfacing with Staubli CS8 robot controllers. This package is part of the

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ROS-Industrial program and contains a VAL3 application and libraries that implement an industrial_robot_client compatible server program. See the readme and wiki for more information.

staubli_val3_driver - ROS Wiki

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